

The Basic Theorem and its Consequences

Noha Eftekhari

Department of Mathematics, Faculty of Sciences, ShahreKord University,
P.O.Box 115, ShahreKord, Iran

E-mail: Eftekharinoha@Yahoo.com

ABSTRACT. Let \mathcal{T} be a compact Hausdorff topological space and let \mathcal{M} denote an n -dimensional subspace of the space $\mathbf{C}(\mathcal{T})$, the space of real-valued continuous functions on \mathcal{T} and let the space be equipped with the uniform norm. Zukhovitskii [7] attributes the Basic Theorem to E.Ya.Remez and gives a proof by duality. He also gives a proof due to Shnirel'man, which uses Helly's Theorem, now the paper obtains a new proof of the Basic Theorem. The significance of the Basic Theorem for us is that it reduces the characterization of a best approximation to $f \in \mathbf{C}(\mathcal{T})$ from \mathcal{M} to the case of finite \mathcal{T} , that is to the case of approximation in $l^\infty(r)$. If one solves the problem for the finite case of \mathcal{T} then one can deduce the solution to the general case. An immediate consequence of the Basic Theorem is that for a finite dimensional subspace \mathcal{M} of $C_0(\mathcal{T})$ there exists a separating measure for \mathcal{M} and $f \in C_0(\mathcal{T}) \setminus \mathcal{M}$, the cardinality of whose support is not greater than $\dim \mathcal{M} + 1$. This result is a special case of a more general abstract result due to Singer [5]. Then the Basic Theorem is used to obtain a general characterization theorem of a best approximation from \mathcal{M} to $f \in \mathbf{C}(\mathcal{T})$. We also use the Basic Theorem to establish the sufficiency of Haar's condition for a subspace \mathcal{M} of $\mathbf{C}(\mathcal{T})$ to be Chebyshev.

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1. INTRODUCTION

Throughout this paper the setting will be as follows: \mathcal{T} will be a compact Hausdorff topological space and $\mathbf{C}(\mathcal{T})$ will denote the space of real continuous functions on \mathcal{T} and \mathcal{M} is an n -dimensional subspace of $\mathbf{C}(\mathcal{T})$. The spaces $\mathbf{C}(\mathcal{T})$ are equipped with the uniform norm. The uniform norm is defined by

$$\|f\| = \max_{t \in \mathcal{T}} |f(t)| \text{ for all } f \in \mathbf{C}(\mathcal{T}),$$

and

$$d(f, \mathcal{M}) = \inf_{g \in \mathcal{M}} \|f - g\| \text{ for } f \in \mathbf{C}(\mathcal{T}),$$

is called the distance from f to \mathcal{M} . We denote by

$$P_{\mathcal{M}}(f) = \{g \in \mathcal{M} : \|f - g\| = d(f, \mathcal{M})\},$$

the set of best approximations to f from \mathcal{M} .

The space $M(\mathcal{T})$ of bounded real valued Borel measures on \mathcal{T} is isometrically isomorphic to the space of bounded linear functionals on $\mathbf{C}(\mathcal{T})$. There is a nonzero $\lambda \in M(\mathcal{T})$ such that $\lambda g < \lambda h$, for all $g \in \mathcal{M}$ and $h \in B(f, d(f, \mathcal{M}))$, the open ball with center f and radius $d(f, \mathcal{M})$. We will call such a measure a *separating measure* for f and \mathcal{M} . A set W is said to be a *Chebyshev subset* of $\mathbf{C}(\mathcal{T})$ if for each $f \in \mathbf{C}(\mathcal{T})$, the set $P_W(f)$ is a single point.

The paper obtains a characterization of Chebyshev hyperplanes in $l^\infty(n)$ (Theorem 2.1) and then by using it we state a characterization theorem for the best approximation from a Chebyshev hyperplane \mathcal{M} of $l^\infty(n)$ (Theorem 2.3). Cheney [2] gives a necessary and sufficient condition for $g \in \mathcal{M}$ not to be a best approximation to $f \in \mathbf{C}(\mathcal{T})$. We give an alternative proof of Cheney's characterization (Theorem 3.1), and then use it to give a new proof of the Basic Theorem 3.2: there exists a finite subset A of \mathcal{T} such that $d(f|_A, \mathcal{M}|_A) = d(f, \mathcal{M})$ and $\text{card } A \leq \dim \mathcal{M} + 1$. Zukhovitskii [7] attributes the Basic Theorem to E.Ya.Remez and gives a proof by duality. He also gives a proof due to Shnirel'man, which uses Helly's Theorem. The significance of the Basic Theorem for us is that it reduces the characterization of a best approximation to f from \mathcal{M} to the case of finite \mathcal{T} , that is to the case of approximation in $l^\infty(r)$. If one solves the problem for the finite case of \mathcal{T} then one can deduce the solution to the general case. A set, the existence of which is asserted by Theorem 3.2, will be called a "basic set". An immediate consequence of the Basic Theorem is that for a finite dimensional subspace \mathcal{M} of $C_0(\mathcal{T})$ there exists a separating measure for \mathcal{M} and $f \in C_0(\mathcal{T}) \setminus \mathcal{M}$, the cardinality of whose support is not greater than $\dim \mathcal{M} + 1$. This result is a special case of a more general abstract result due to Singer [5]. Theorem 3.9 and Theorem 2.3 characterize Chebyshev hyperplanes in $l^\infty(n)$ and best approximations from them. Then the Basic Theorem is used to obtain a general characterization theorem

(Theorem 3.11) of a best approximation from \mathcal{M} to $f \in \mathbf{C}(\mathcal{T})$. The latter theorem is equivalent to Theorem 3.12 which is the extension to a general \mathcal{M} , not necessary Chebyshev, of the Chebyshev Alternation Theorem. We also use the Basic Theorem to establish the sufficiency of Haar's condition for a subspace \mathcal{M} of $\mathbf{C}(\mathcal{T})$ to be Chebyshev (Theorem 3.10).

Let $0 \neq f \in \mathbf{C}(\mathcal{T})$. The critical set is

$$\text{crit } f = \{t \in \mathcal{T} : |f(t)| = \|f\|\} .$$

Define

$$e : \mathcal{T} \longrightarrow \mathcal{M}^* \text{ by } e(t)(g) = g(t) , \text{ for all } g \in \mathcal{M} .$$

Let $A \subseteq \mathcal{T}$. The following conditions are equivalent.

- (1) For $g \in \mathcal{M} \setminus \{0\}$, $\text{card } g^{-1}(0) \leq n - 1$ (the Haar condition).
- (2) For each set $A = \{t_1, \dots, t_n\}$ of n distinct points the mapping $S : \mathcal{M} \rightarrow \mathbb{R}^n$, defined by $S(g) = (g(t_1), \dots, g(t_n))$, is injective.
- (3) For each set $A = \{t_1, \dots, t_n\}$ of n distinct points the mapping $S : \mathcal{M} \rightarrow \mathbb{R}^n$ is surjective.
- (4) For each set $A = \{t_1, \dots, t_n\}$ of n distinct points $\dim \mathcal{M}|_A = n$.
- (5) If $r \leq n$ and t_1, \dots, t_r are distinct points of \mathcal{T} then $e(t_1), \dots, e(t_r)$ are linearly independent points of \mathcal{M}^* .
- (6) If $A \subseteq \mathcal{T}$ and $\text{card } A \leq n$ then $\mathcal{M}|_A = C(A)$.

The following theorems are required.

Theorem 1.1. ([4, Lemma 2.2.1]) *Let $f \in \mathbf{C}(\mathcal{T})$ and let f be not identically zero. Let \mathcal{M} be a subspace of $\mathbf{C}(\mathcal{T})$. A necessary and sufficient condition that $0 \in P_{\mathcal{M}}(f)$ is that, there is no $g \in \mathcal{M} \setminus \{0\}$ such that*

$$f(t)g(t) > 0 , \text{ for all } t \in \text{crit } f.$$

Theorem 1.2. (The basic separation theorem)([3, Theorem 3.4]) *Suppose A and B are disjoint, nonempty, convex sets in a topological vector space \mathcal{X} .*

- (a) *If A is open there exist $\varphi \in \mathcal{X}^*$ and $\gamma \in \mathbb{R}$ such that*

$$\varphi(x) < \gamma \leq \varphi(y) \text{ for every } x \in A \text{ and for every } y \in B.$$

- (b) *If A is compact, B is closed, and \mathcal{X} is locally convex, then there exist $\varphi \in \mathcal{X}^*$, $\gamma_1 \in \mathbb{R}$, $\gamma_2 \in \mathbb{R}$, such that*

$$\varphi(x) < \gamma_1 < \gamma_2 < \varphi(y) \text{ for every } x \in A \text{ and for every } y \in B.$$

Theorem 1.3. (Caratheodory's theorem) *Let A be a subset of an n -dimensional linear space. Every point of the convex hull of A is expressible as a convex combination of $n + 1$ (or fewer) elements of A .*

Theorem 1.4. (*The Chebyshev Alternation Theorem*) Let $f \in C([a, b])$. A polynomial $p \in P_{n-1}$ is a best approximation to f if and only if there exist $n + 1$ points $a \leq t_0 < t_1 < \dots < t_n \leq b$ and $\varepsilon \in \{-1, 1\}$ such that

$$(f - p)(t_j) = \varepsilon(-1)^j \|f - p\| \text{ for } j = 0, \dots, n.$$

($f - p$ has n alternations on $[a, b]$).

2. CHEBYSHEV HYPERPLANES IN $l^\infty(n)$

In this section we establish those restricted finite dimensional results for approximation by hyperplanes in $l^\infty(n)$ from which, using the Basic Theorem, the classical results for best approximation from a subspace \mathcal{M} of $\mathbf{C}(\mathcal{T})$ will be deduced.

It is a geometrically obvious fact that if $\mathcal{M} = \varphi^{-1}(0)$ is a hyperplane in a normed linear space \mathcal{X} then \mathcal{M} is Chebyshev if and only if $\{x \in \mathcal{X} : \|x\| = 1 \text{ and } \varphi(x) = \|\varphi\|\}$ is a single point. Interpreting this in the case $\mathcal{X} = l^\infty(n)$ we obtain a characterization of Chebyshev hyperplanes in $l^\infty(n)$.

Theorem 2.1. Let $\varphi = (\varphi_1, \dots, \varphi_n) \in l^1(n) \setminus \{0\}$. A hyperplane $\mathcal{M} = \varphi^{-1}(0)$ of $l^\infty(n)$ is Chebyshev if and only if $\varphi_k \neq 0$ for all $k = 1, \dots, n$.

Proof. Let $f = (f(1), \dots, f(n)) \in l^\infty(n) \setminus \mathcal{M}$. So $\varphi(f) = \sum_{k=1}^n \varphi_k f(k)$ and $\|\varphi\| \|f\| = \sum_{k=1}^n |\varphi_k| \cdot \|f\|$. Thus $\varphi(f) = \|\varphi\| \|f\|$ if and only if $f(k) = \text{sgn } \varphi_k \cdot \|f\|$ when $\varphi_k \neq 0$. Therefore $\{f : \|f\| = 1, \varphi(f) = \|\varphi\|\}$ is a single point if and only if $\varphi_k \neq 0$ for all $k = 1, \dots, n$. \square

Corollary 2.2. If \mathcal{M} is a Chebyshev hyperplane in $l^\infty(n)$ and $A \subset \{1, 2, \dots, n\}$ then $\mathcal{M}|_A = l^\infty(A)$.

Proof. Let $\mathcal{M} = \varphi^{-1}(0)$ where $\varphi \in l^1(n) \setminus \{0\}$. Then by Theorem 2.1, $\varphi = \sum_{k=1}^n \varphi_k e_{\mathcal{T}}(k)$ and $\varphi_k \neq 0$ for $k = 1, \dots, n$. Now suppose, on the contrary, that $\mathcal{M}|_A \subset l^\infty(A)$. Then there exists $\psi \in l^1(A) \setminus \{0\}$ such that $\mathcal{M}|_A \subseteq \psi^{-1}(0)$. So $\psi(g|_A) = 0$ for all $g \in \mathcal{M}$. Let $\psi = \sum_{i \in A} c_i e_A(i)$. Thus $\sum_{i \in A} c_i g(i) = 0$ for all $g \in \mathcal{M}$. That is, $(\sum_{i \in A} c_i e_{\mathcal{T}}(i))(g) = 0$ for all $g \in \mathcal{M} = \varphi^{-1}(0)$. So $\sum_{i \in A} c_i e_{\mathcal{T}}(i) = \alpha \varphi = \alpha \sum_{i=1}^n \varphi_i e_{\mathcal{T}}(i)$ for some α . Therefore, $\alpha = 0$ and c_i are all zero and so $\psi \equiv 0$ which is a contradiction. So $\mathcal{M}|_A = l^\infty(A)$. \square

The next theorem characterizes the best approximation from a Chebyshev hyperplane \mathcal{M} of $l^\infty(n)$.

Theorem 2.3. Let \mathcal{M} be a Chebyshev hyperplane subspace of $l^\infty(n)$. Let $f \in l^\infty(n) \setminus \mathcal{M}$ and $g \in \mathcal{M}$. Then $g \in P_{\mathcal{M}}(f)$ if and only if $(f - g)(i) = \text{sgn } c(i) \|f - g\|$, for $i = 1, \dots, n$, where $\varphi = (c(1), \dots, c(n)) \in l^1(n)$ and $\|\varphi\|_1 = 1, \varphi \in \mathcal{M}^\perp$ and all $c(i)$ are nonzero.

Proof. By General Characterization Theorem [1, Theorem 1]

$$\begin{aligned} g \in P_{\mathcal{M}}(f) &\Leftrightarrow \varphi(f - g) = \|\varphi\| \|f - g\|, \|\varphi\| = 1, \varphi \in \mathcal{M}^{\perp}, \\ &\Leftrightarrow (f - g)(i) = \operatorname{sgn} c(i) \|f - g\|, \text{ for } i = 1, \dots, n, \varphi \in \mathcal{M}^{\perp}. \end{aligned}$$

Also by Theorem 2.1, $c(i) \neq 0$ for $i = 1, \dots, n$. \square

3. THE BASIC THEOREM AND ITS RESULTS

In this section, we will prove “Basic Theorem”. It is important for us because investigation of best approximation to $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$ from \mathcal{M} reduces to the case of finite \mathcal{T} , that is, in finite space $l^{\infty}(r)$. A set, the existence of which is asserted by the theorem, will be called a “basic set”. The Basic Theorem has worthwhile results. We develop of the Chebyshev theory of best uniform approximation using the Basic Theorem. The extension to a general (not necessarily Chebyshev) \mathcal{M} of the Chebyshev Alternation Theorem (3.11 and 3.12) will be obtained by exploiting the Basic Theorem.

The following theorem has been proved in Chapter 3 of [2] and we give an alternative proof of it.

Theorem 3.1. (Characterization Theorem) *In order that $g \in \mathcal{M}$ is not a best approximation to $f \in \mathbf{C}(\mathcal{T})$, it is necessary and sufficient that $0 \in \mathcal{M}^*$ is not in the convex hull of the set $\{h(t)e(t) : |h(t)| = \|h\|\}$, where $h = g - f$.*

Proof. (Use basic separation theorem) Let $\mathcal{T}_0 = \operatorname{crit} h$. Since h is a continuous function, then \mathcal{T}_0 is a closed subset of the compact set \mathcal{T} and so \mathcal{T}_0 is a compact set.

Let $A = \{h(t)e(t) : t \in \mathcal{T}_0\}$. The function he is continuous on the compact set \mathcal{T}_0 and so A is a compact subset of \mathcal{M}^* . Since \mathcal{M}^* is finite dimensional then $K = \operatorname{co} A$ is compact in \mathcal{M}^* and K is closed convex subset of \mathcal{M}^* . By Theorem 1.2, it follows that, $0 \notin K$ if and only if there exists $\varphi \in (\mathcal{M}^*)^* \setminus \{0\}$ such that $\varphi(k) > 0$ for all, $k \in K$. Since $(\mathcal{M}^*)^* \cong \mathcal{M}$ then it is equivalent to there exists $g' \in \mathcal{M} \setminus \{0\}$ such that $k(g') > 0$ for all, $k \in K$. So it is equivalent to there exists $g' \in \mathcal{M} \setminus \{0\}$ such that $(h(t)e(t))(g') > 0$ for all $t \in \mathcal{T}_0$. Since $e(t)(g') = g'(t)$, it means that, there exists $g' \in \mathcal{M} \setminus \{0\}$ such that $h(t)g'(t) > 0$, for all $t \in \mathcal{T}_0$ and so by Theorem 1.1, $g \in \mathcal{M}$ is not a best approximation to f . \square

In the following, we give a new proof of the Basic Theorem.

Theorem 3.2. (Basic Theorem) *Let $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$. Then there exist r points $t_1, \dots, t_r \in \mathcal{T}$ such that*

$$d(f, \mathcal{M}) = d(f|_A, \mathcal{M}|_A),$$

where $A = \{t_1, \dots, t_r\}$ and $\operatorname{card} A \leq \dim \mathcal{M} + 1$.

Proof. Let $g \in P_{\mathcal{M}}(f)$ and $h = g - f$. That is, $d(f, \mathcal{M}) = \|f - g\| = \|h\|$. Let $\mathcal{T}_0 = \text{crit } h$. Theorem 3.1 (Characterization Theorem) implies that $0 \in K = \text{co} \{ h(t) e(t) : t \in \mathcal{T}_0 \}$. The set $\{ h(t) e(t) : t \in \mathcal{T}_0 \}$ is a subset of n -dimensional space \mathcal{M}^* and so it follows from Caratheodory's theorem (Theorem 1.3) that $\sum_{i=1}^r \alpha_i h(t_i) e(t_i) = 0$, for some t_1, \dots, t_r in \mathcal{T}_0 and some positive numbers $\alpha_1, \dots, \alpha_r$ with $\sum_{i=1}^r \alpha_i = 1$, where $r \leq \dim \mathcal{M} + 1$. Let $A = \{t_1, \dots, t_r\}$ and $e_{\mathcal{M}|_A} : \mathcal{T} \rightarrow (\mathcal{M}|_A)^*$. Then $0 \in \text{co} \{ h(t) e_{\mathcal{M}|_A}(t) : t \in A \}$. One can apply Theorem 3.1 (Characterization Theorem) to A , $\mathcal{M}|_A$ and $g|_A \in P_{\mathcal{M}|_A}(f|_A)$ and get $d(f|_A, \mathcal{M}|_A) = \|(f - g)|_A\| = \|h\| = \|f - g\| = d(f, \mathcal{M})$. \square

Remark 3.3. In the Basic Theorem $1 \leq r \leq n + 1$ in the real case and $1 \leq r \leq 2n + 1$ in the complex case, because of, $\mathbb{C}^n = \mathbb{R}^{2n}$. Also, we call $A \subseteq \mathcal{T}$ a "basic set" for \mathcal{M} and f if it is finite and such that $d(f, \mathcal{M}) = d(f|_A, \mathcal{M}|_A)$.

The significance of the Basic Theorem is that it reduces the characterization of best approximation to f from \mathcal{M} to the case of finite \mathcal{T} , that is to the case of approximation in $l^\infty(r)$. If one solves the problem for the finite case of \mathcal{T} then one can deduce the solution to the general case.

The Basic Theorem implies the following corollaries.

Corollary 3.4. *Let $f \in \mathbf{C}(\mathcal{T})$ and $g \in \mathcal{M}$. Let $A \subseteq \mathcal{T}$ be a basic set for \mathcal{M} and f . Then $g \in P_{\mathcal{M}}(f)$ if and only if $\|f - g\| = \|(f - g)|_A\|$ and $g|_A \in P_{\mathcal{M}|_A}(f|_A)$.*

Proof. Let $g \in P_{\mathcal{M}}(f)$. By the Basic Theorem,

$$d(f|_A, \mathcal{M}|_A) = d(f, \mathcal{M}) = \|f - g\| \geq \|(f - g)|_A\| \geq d(f|_A, \mathcal{M}|_A),$$

which implies that $\|f - g\| = \|(f - g)|_A\|$ and $g|_A \in P_{\mathcal{M}|_A}(f|_A)$. Now assume that, $g|_A \in P_{\mathcal{M}|_A}(f|_A)$ and $\|f - g\| = \|(f - g)|_A\| = d(f|_A, \mathcal{M}|_A) = d(f, \mathcal{M})$ (the Basic Theorem implies the last equality). Therefore $g \in P_{\mathcal{M}}(f)$. \square

Corollary 3.5. *Let $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$. Let $A \subseteq \mathcal{T}$ be a minimal basic set for \mathcal{M} and f . Then $A \subseteq \text{crit}(f - P_{\mathcal{M}}(f)) = \bigcap_{g \in P_{\mathcal{M}}(f)} \text{crit}(f - g)$.*

Proof. Let $g \in \text{relint } P_{\mathcal{M}}(f)$. From Corollary 3.4 it follows that

$$\|(f - g)|_A\| = \|f - g\| = \|(f - g)|_{\text{crit}(f - g)}\|.$$

So $\emptyset \neq A \cap \text{crit}(f - g) \subseteq A$ and it will be shown that $B = A \cap \text{crit}(f - g)$ is a basic set for \mathcal{M} and f . If $B = A$ then there is nothing to prove. Now if $a \in A \setminus B$ then $|(f - g)(a)| < \|f - g\|$. Suppose, on the contrary, that $d(f|_B, \mathcal{M}|_B) < d(f|_A, \mathcal{M}|_A)$. Choose $g' \in \mathcal{M}$ such that $g'|_B \in P_{\mathcal{M}|_B}(f|_B)$. So

$$\|(f - g')|_B\| = d(f|_B, \mathcal{M}|_B) < d(f|_A, \mathcal{M}|_A) = \|(f - g)|_A\|.$$

Now for $\theta \in (0, 1)$, consider

$$\begin{aligned} \|(f - ((1 - \theta)g' + \theta g))|_A\| &= \max\{ \max_{a \in A \setminus B} |(f - ((1 - \theta)g' + \theta g))(a)|, \\ &\quad \|(f - ((1 - \theta)g' + \theta g))|_B\| \}. \end{aligned}$$

Since $|(f - g)(a)| < \|f - g\|$ and the set $\{|(f - g')(a)| : a \in A \setminus B\}$ is bounded so for θ close to 1, $\max_{a \in A \setminus B} |(f - ((1 - \theta)g' + \theta g))(a)| < \|f - g\|$, also $\|(f - g')|_B\| < \|f - g\|$ and $\|(f - g)|_B\| \leq \|(f - g)|_A\| = \|f - g\|$. Thus

$$\|(f - ((1 - \theta)g' + \theta g))|_A\| < \|f - g\|,$$

which is a contradiction. Therefore, $B = A \subseteq \text{crit}(f - g)$ is a basic set for \mathcal{M} and f and so by next remark $A \subseteq \text{crit}(f - P_{\mathcal{M}}(f))$. \square

Remark 3.6. If $g \in \text{relint } P_{\mathcal{M}}(f)$ then

$$\text{crit}(f - g) = \text{crit}(f - P_{\mathcal{M}}(f)).$$

Because, let $t \in \text{crit}(f - g)$ and let $g' \in P_{\mathcal{M}}(f) \setminus \{g\}$. Then $g \in (g', g'')$ for some $g'' \in P_{\mathcal{M}}(f)$. That is, for some $\theta \in (0, 1)$, $g = (1 - \theta)g' + \theta g''$ and

$$\begin{aligned} d(f, \mathcal{M}) = \|f - g\| &= |(f - g)(t)| \leq (1 - \theta)|(f - g')(t)| + \theta|(f - g'')(t)| \\ &\leq (1 - \theta)\|f - g'\| + \theta\|f - g''\| = d(f, \mathcal{M}). \end{aligned}$$

So $t \in \text{crit}(f - g')$. That is, $\text{crit}(f - g) = \text{crit}(f - P_{\mathcal{M}}(f))$.

The following theorem is an immediate consequence of the Basic Theorem.

Theorem 3.7. *Let $f \in C_0(\mathcal{T}) \setminus \mathcal{M}$. Then there exists a separating measure φ , for f and \mathcal{M} , such that $|\text{supp } \varphi| \leq \dim \mathcal{M} + 1$.*

Proof. Let A be a minimal basic set for \mathcal{M} and f . If $\varphi \in (\mathcal{M}|_A)^*$ is a separating measure for $f|_A$ and $\mathcal{M}|_A$. Then φ is of the form $\varphi = \sum_{i \in A} c(i) e(i)$, ($e(i) \in C(A)^*$). The functional φ has the natural extension $\bar{\varphi} = \sum_{i \in A} c(i) e(i)$, ($e(i) \in C_0(\mathcal{T})^*$) and $\bar{\varphi}$ is a separating measure for f and \mathcal{M} . Therefore, $|\text{supp } \bar{\varphi}| = \text{card } A \leq \dim \mathcal{M} + 1$. (By the Basic Theorem.) \square

Theorem 3.8. *Let $f \in C(\mathcal{T}) \setminus \mathcal{M}$. Let A be a minimal basic set for \mathcal{M} and f . Then $\mathcal{M}|_A$ is a Chebyshev hyperplane in $C(A)$.*

Proof. Apply the Basic Theorem to $C(A)$, $\mathcal{M}|_A$ and $f|_A$ then there exists a minimal basic set $A_1 \subseteq A$ such that $\text{card } A_1 \leq \dim \mathcal{M}|_A + 1$ and $d(f, \mathcal{M}) = d(f|_A, \mathcal{M}|_A) = d(f|_{A|_{A_1}}, \mathcal{M}|_{A|_{A_1}}) = d(f|_{A_1}, \mathcal{M}|_{A_1})$. By minimality of A , it follows that $A_1 = A$. So

$$\dim C(A) \leq \text{card } A \leq \dim \mathcal{M}|_A + 1.$$

But $f|_A \notin \mathcal{M}|_A$ so $\dim \mathcal{M}|_A = \dim C(A) - 1$. That is, $\mathcal{M}|_A$ is a hyperplane in $C(A)$.

By Corollary 3.5, $A = A_1 \subseteq \text{crit}(f|_A - P_{\mathcal{M}|_A}(f|_A))$ and so all functions of $P_{\mathcal{M}|_A}(f|_A)$ coincide on A , that is $P_{\mathcal{M}|_A}(f|_A)$ is a single point. Thus $\mathcal{M}|_A$ is Chebyshev in $C(A)$. \square

Theorem 3.9. *Let $n > 1$. A hyperplane \mathcal{M} of $l^\infty(n)$ is Chebyshev if and only if $A = \{1, 2, \dots, n\}$ is the only basic set.*

Proof. (\Rightarrow) By Corollary 2.2.

(\Leftarrow) By Theorem 3.8. \square

Theorem 3.10. (*Haar's Theorem*) *Let \mathcal{M} be a finite dimensional subspace of $\mathbf{C}(\mathcal{T})$. Then \mathcal{M} satisfies the Haar Condition if and only if \mathcal{M} is a Chebyshev subspace of $\mathbf{C}(\mathcal{T})$.*

Proof. (\Rightarrow) Let $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$ and $\dim \mathcal{M} = n$. Let $A = \{t_1, \dots, t_r\}$ be a minimal basic set for \mathcal{M} and f . Suppose that $r \leq n$. Then $e_{\mathcal{M}|_A}(t_1), \dots, e_{\mathcal{M}|_A}(t_r)$ are linearly independent (equivalent to Haar Condition). So $\dim \mathcal{M}|_A = r$ and $\mathcal{M}|_A = C(A)$ which contradicts $d(f|_A, \mathcal{M}|_A) = d(f, \mathcal{M}) \neq 0$. Thus $r = n + 1$. So the restriction mapping $r_A : \mathcal{M} \rightarrow \mathcal{M}|_A$ is injective and $\mathcal{M}|_A$ is Chebyshev in $C(A)$ (Theorem 3.8) and $r_A(P_{\mathcal{M}}(f)) \subseteq P_{\mathcal{M}|_A}(f|_A)$. Thus $P_{\mathcal{M}}(f)$ is a single point. That is, \mathcal{M} is a Chebyshev subspace of $\mathbf{C}(\mathcal{T})$.

Now (\Leftarrow), by any known proof of Haar's Theorem. \square

Now by Corollary 3.4, Theorem 3.8 and Theorem 2.3, one can obtain the following general characterization theorem. Singer [6] obtained a more general abstract characterization theorem of which, this is a special case.

Theorem 3.11. *Let $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$ and $g \in \mathcal{M}$. Then $g \in P_{\mathcal{M}}(f)$ if and only if there exists a nonempty finite subset $A = \{t_1, \dots, t_r\}$ of \mathcal{T} , $1 \leq r \leq n + 1$, and nonzero $c(t)$ for $t \in A$ with $\sum_{t \in A} |c(t)| = 1$ such that*

- (1) $\sum_{t \in A} c(t)e(t) \in \mathcal{M}^\perp$, and;
- (2) $f(t) - g(t) = \text{sgn } c(t) \|f - g\|$, for $t \in A$.

Proof. Let A be a minimal basic set for \mathcal{M} and f ($\text{card } A \leq \dim \mathcal{M} + 1 = n + 1$). By Corollary 3.4, $g \in P_{\mathcal{M}}(f)$ if and only if $g|_A \in P_{\mathcal{M}|_A}(f|_A)$ and $\|f - g\| = \|(f - g)|_A\|$. By Theorem 3.8 and Theorem 2.3, it is equivalent to there exists a non-zero $c(t)$ for $t \in A$ with $\sum_{t \in A} |c(t)| = 1$ such that

- (1) $\sum_{t \in A} c(t)e(t) \in \mathcal{M}^\perp$, and;
- (2) $f(t) - g(t) = \text{sgn } c(t) \|f - g\|$, for $t \in A$.

\square

If r is the smallest integer such that Theorem 3.11 is satisfied then we obtain the following characterization theorem.

Theorem 3.12. *Let $f \in \mathbf{C}(\mathcal{T}) \setminus \mathcal{M}$ and $g \in \mathcal{M}$. Then $g \in P_{\mathcal{M}}(f)$ if and only if there exists a nonempty finite subset $A = \{t_1, \dots, t_r\}$ of \mathcal{T} , where $1 \leq r \leq n + 1$ with the following properties,*

- (i) *The rank of the matrix:*

$$G = \begin{bmatrix} g_1(t_1) & \dots & g_1(t_r) \\ \vdots & \vdots & \vdots \\ g_n(t_1) & \dots & g_n(t_r) \end{bmatrix}$$

is less than r , where $\{g_1, \dots, g_n\}$ is a basis of \mathcal{M} .

(ii) The matrix

$$\begin{bmatrix} g_1(t_1) & \dots & g_1(t_r) \\ \vdots & \vdots & \vdots \\ g_n(t_1) & \dots & g_n(t_r) \\ f(t_1) & \dots & f(t_r) \end{bmatrix}$$

is of rank r .

(iii) Among the minors of order r of the matrix in part (ii), there exists at least a minor $\Delta \neq 0$ in which all cofactors Δ_j of the elements $f(t_j)$, $j = 1, \dots, r$ are nonzero.

(iv) The following equalities are satisfied,

$$f(t_j) - g(t_j) = \left(\operatorname{sgn} \frac{\Delta_j}{\Delta}\right) \|f - g\|, \text{ for } j = 1, \dots, r.$$

Proof. The Theorem 3.12 is a translation of the Theorem 3.11 (modified if necessary).

(i) , (iii) \Leftrightarrow (1) and the fact that all $c(t)$ are nonzero for $t \in A$. Also, r is minimal and $\dim \mathcal{M}|_A = r - 1$.

(ii) $\Leftrightarrow f|_A \notin \mathcal{M}|_A$ which relates to A is minimal.

(iv) \Leftrightarrow (2) □

This result, attributed by Zuhovitskii to Remez is the generalization of the Chebyshev Alternation Theorem for Chebyshev $\mathcal{M} \subseteq C([0, 1])$ to a general (not necessary Chebyshev) $\mathcal{M} \subseteq \mathbf{C}(\mathcal{T})$. If the theorem is specialized to $\mathcal{T} = [0, 1]$ and \mathcal{M} Chebyshev, then it yields the alternation theorem.

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